

Class Notes for the Course AerE 310

Aerodynamics 1

Prepared by

Dr. Hui Hu

Department of Aerospace Engineering

Iowa State University

2271 Howe Hall - Room 1200, Ames, IA 50011-2271

Tel: 515-294-0094 (Office) / Email: huhui@iastate.edu

Department of Aerospace Engineering

Iowa State University

August 15, 2021

Chapter 1

Review of Multivariable Calculus

1.1. Review of Partial Differentials and Chain Rule

1.1.1 Definition of Partial Differentials

$$f_x(x_0, y_0) = \lim_{\Delta x \rightarrow 0} \left[\frac{f(x_0 + \Delta x, y_0) - f(x_0, y_0)}{\Delta x} \right]$$
$$f_y(x_0, y_0) = \lim_{\Delta y \rightarrow 0} \left[\frac{f(x_0, y_0 + \Delta y) - f(x_0, y_0)}{\Delta y} \right]$$

1.1.2 Properties of Partial Derivatives

$$(f + g)_y = f_y + g_y;$$
$$(f - g)_y = f_y - g_y;$$
$$(f g)_y = f_y g + f g_y;$$
$$(f / g)_y = \frac{f_y g - f g_y}{g^2}$$
$$(f_x)_x = f_{xx} = \frac{\partial^2 f}{\partial x^2};$$
$$(f_x)_y = f_{xy} = \frac{\partial^2 f}{\partial y \partial x};$$
$$(f_y)_x = f_{yx} = \frac{\partial^2 f}{\partial x \partial y};$$
$$(f_y)_x = (f_x)_y = f_{yx} = f_{xy}$$

1.1.3 Chain Rule

1). In two- dimensional space:

$$\left. \begin{array}{l} z = f(x, y) \\ x = g_1(t) \\ y = g_2(t) \end{array} \right\} \Rightarrow z = z(x, y) = f(g_1(t), g_2(t)) = z(t)$$

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

$$\left. \begin{array}{l} w = f(x, y) \\ x = g_1(u, v) \\ y = g_2(u, v) \end{array} \right\} \Rightarrow w = f(x, y) = f(g_1(u, v), g_2(u, v)) = w(u, v)$$

$$\begin{aligned} \frac{\partial w}{\partial u} &= \frac{\partial w}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial u} \\ \frac{\partial w}{\partial v} &= \frac{\partial w}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial v} \end{aligned}$$

2). In three-dimensional space:

$$\left. \begin{array}{l} w = f(x, y, z) \\ x = g_1(t) \\ y = g_2(t) \\ z = g_3(t) \end{array} \right\} \Rightarrow \frac{dw}{dt} = \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial y} \frac{dy}{dt} + \frac{\partial w}{\partial z} \frac{dz}{dt}$$

$$\left. \begin{array}{l} w = f(x, y, z) \\ x = g_1(u, v) \\ y = g_2(u, v) \\ z = g_3(u, v) \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \frac{\partial w}{\partial u} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial u} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial u} \\ \frac{\partial w}{\partial v} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial v} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial v} \end{array} \right.$$