

LECTURE 05: METHODS FOR LOCAL FLOW VELOCITY MEASUREMENTS: HOTWIRE – ANEMOMETRY PART #01

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Methods to Measure Local Flow Velocity - 1

- *Mechanical methods:*

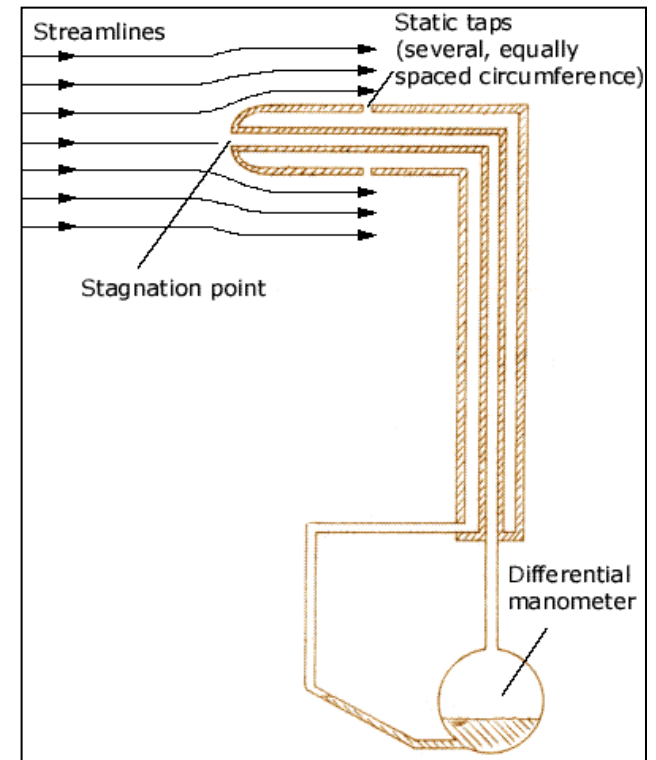
- Taking advantage of force and moments that a moving stream applies on immersed objects.
- Vane anemometers
- Propeller anemometers



□ METHODS TO MEASURE LOCAL FLOW VELOCITY -2

- *Pressure difference methods:*

- Utilize analytical relationship between the local velocity and the static and total pressures.
- Pressure taps sensing **static pressure** (also the reference pressure for this measurement) are placed radially on the probe stem and then combined into one tube leading to the differential manometer (p_{stat}).
- The pressure tap located at the probe tip senses the **stagnation pressure** (p_0).
- Use of the two measured pressures in the Bernoulli equation allows to determine one component of the **flow velocity** at the probe location.
- Special arrangements of the pressure taps (Three-hole, Five-hole, seven-hole Pitot) in conjunction with special calibrations are used to measure all velocity components.
- It is difficult to measure stagnation pressure in real, due to friction. The measured stagnation pressure is always less than the actual one. This is taken care of by an empirical factor C .



$$p_0 = p_{stat} + \frac{1}{2} \rho V^2, (\text{Bernoulli})$$

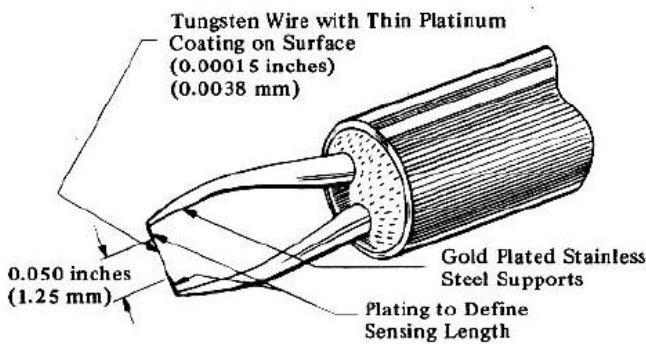
$$V = \sqrt{2(p_0 - p_{stat}) / \rho}$$

$$V = C \sqrt{2(p_0 - p_{stat}) / \rho}$$

❑ METHODS TO MEASURE LOCAL FLOW VELOCITY -3

• Thermal methods:

- Compute flow velocity from its relationship between local flow velocity and the convective heat transfer from heated elements.



Hot wire anemometers

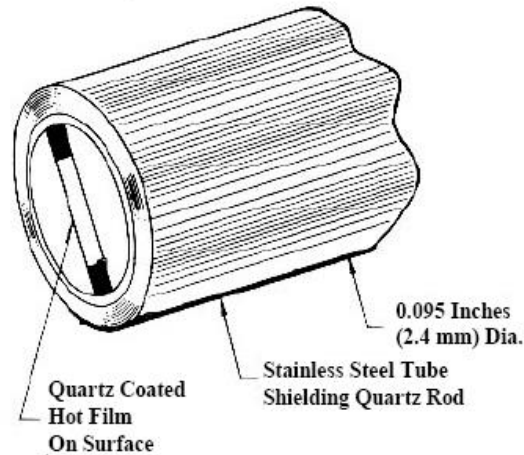


Figure 6: Hot Film Flush Mounted Probe

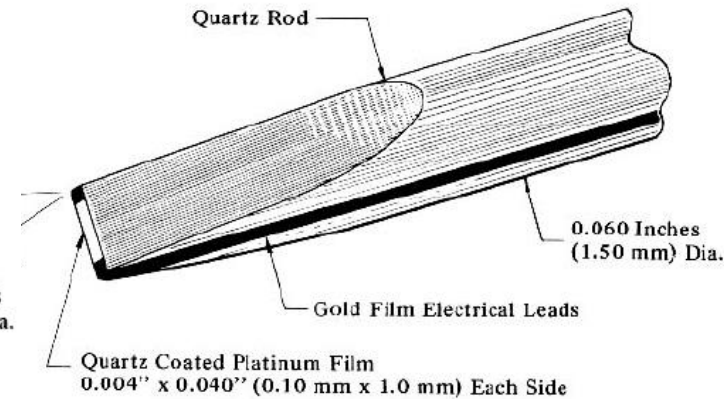
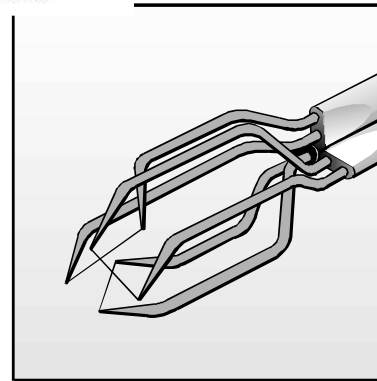
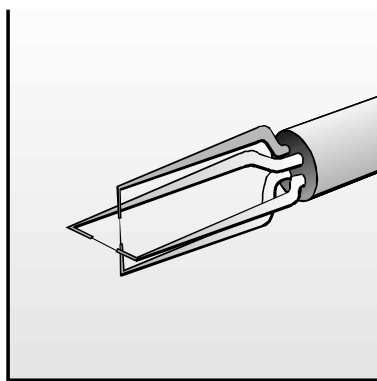
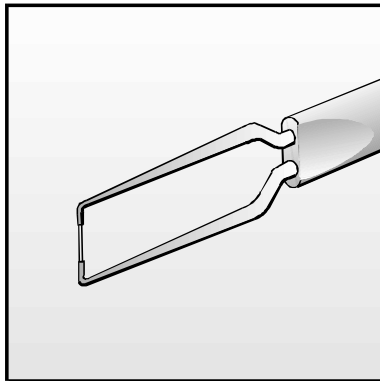


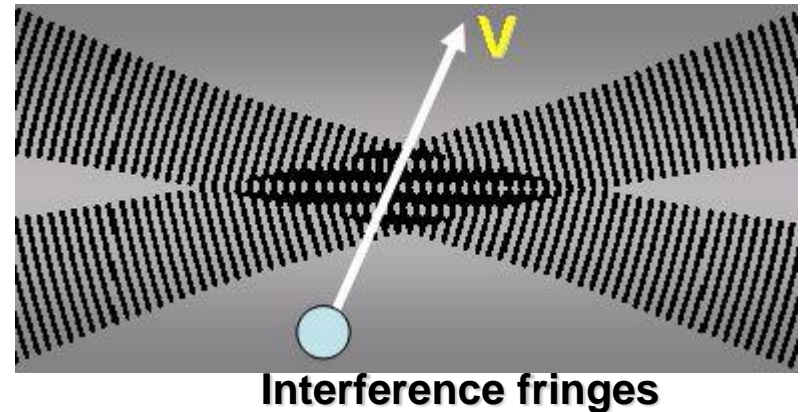
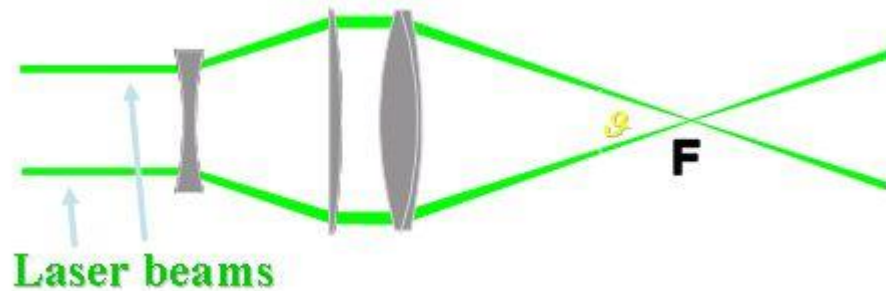
Figure 7: Hot Film Wedge Probe



□ METHODS TO MEASURE LOCAL FLOW VELOCITY - 4

• Frequency-shift methods:

- Based on the Doppler phenomenon, namely the shift of the frequency of waves scattered by moving particles.
- Laser Doppler Velocimetry (LDV) or Laser Doppler Anemometry (LDV)
- Planar Doppler Velocimetry (PDV) or Planar Doppler Anemometry (PDA)

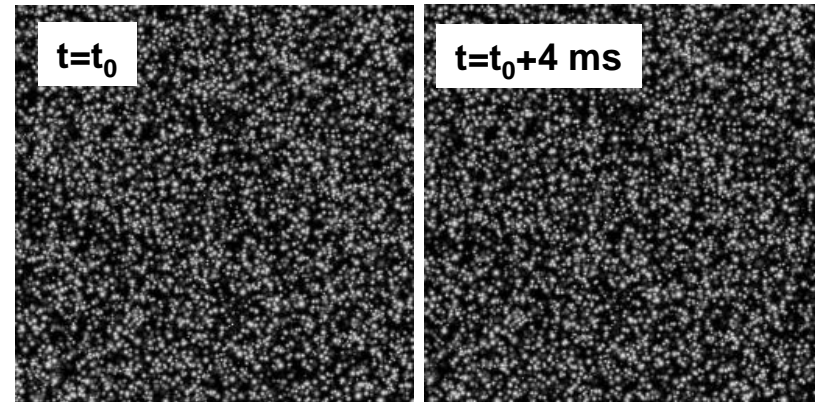


$$v_{\perp} = \frac{\lambda}{2 \sin \frac{\theta}{2}} f$$

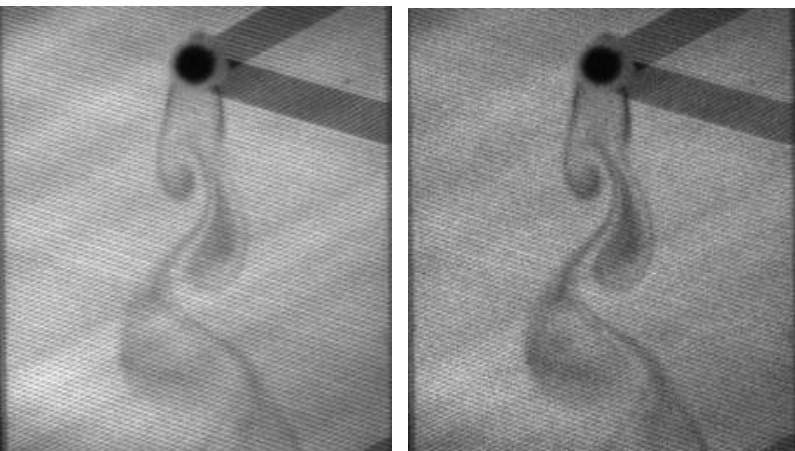
□ METHODS TO MEASURE LOCAL FLOW VELOCITY - 5

• *Marker tracing methods:*

- Trace the motion of suitable flow makers, optically or by other means to derive local flow velocity.
- Particle Imaging Velocimetry (PIV)
- Particle Tracking Velocimetry (PTV)
- Molecular Tagging Velocimetry (MTV)

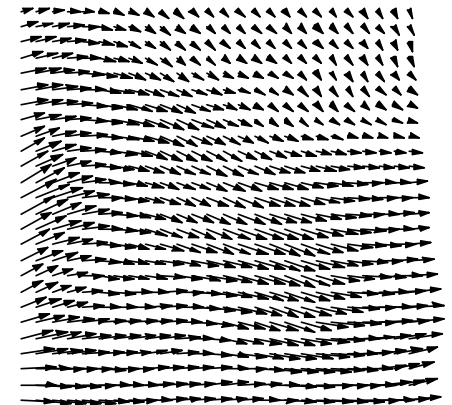
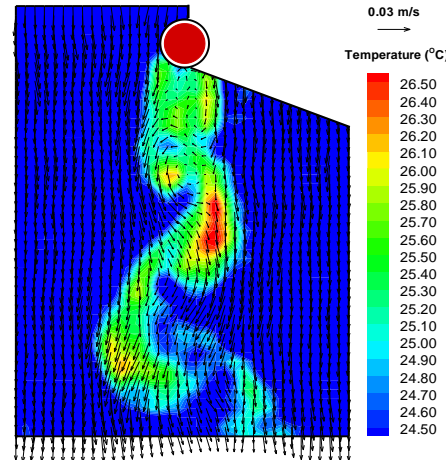


PIV image pair



$t=t_0$

$t=t_0+5\text{ms}$

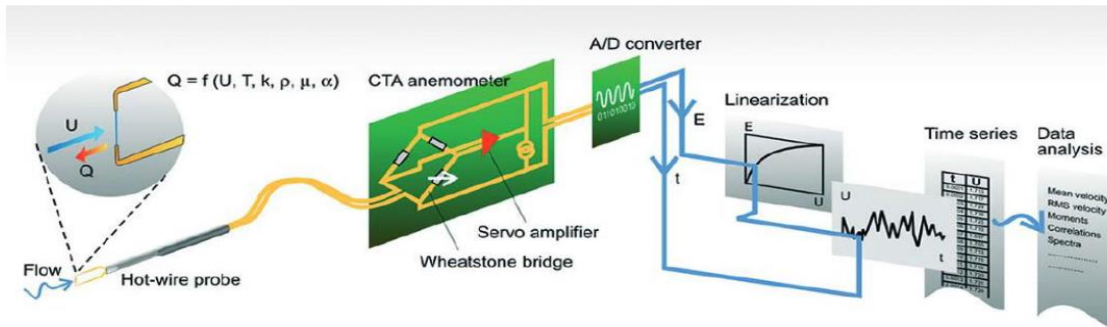


Corresponding flow velocity field

□ How Does A HOT WIRE SENSOR WORK

- **Thermal anemometers:** Measure the local flow velocity through its relationship to the convective cooling of electrically heated metallic sensors.
- **Hot wire anemometers:**
 - for clean air or other gas flows
- **Hot film anemometers:**
 - for liquid or some gas flows

Thermal anemometry – system components:



DantecDynamics



StreamLine Pro - the most reliable research-grade CTA system.



MultichannelCTA - the multiple channel version of the MiniCTA system.



MiniCTA - the most compact CTA system for educational use.

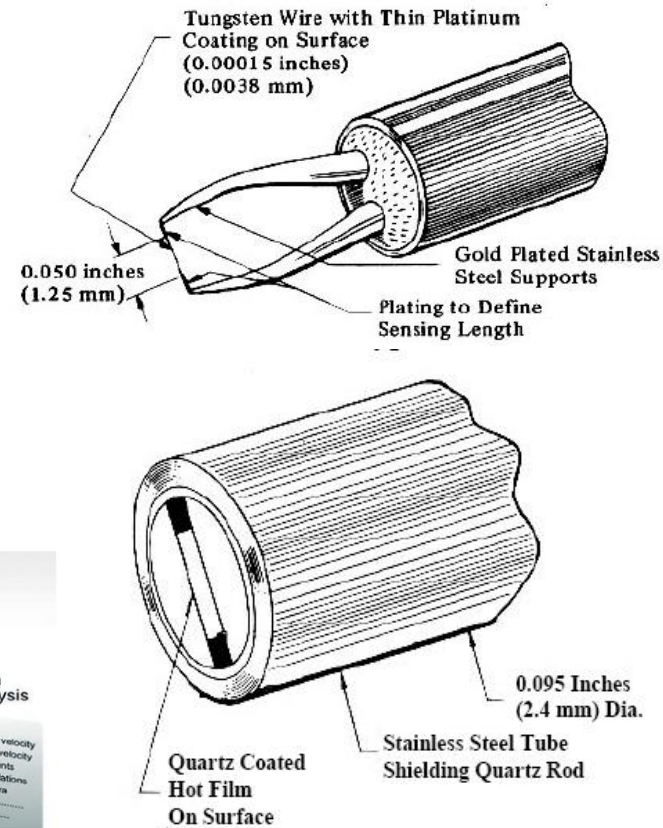


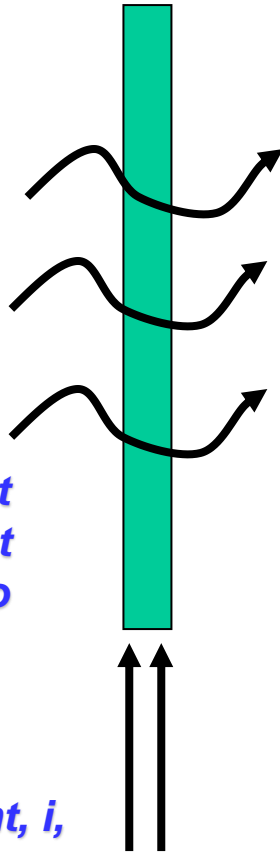
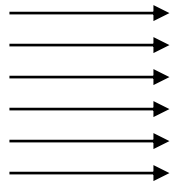
Figure 6: Hot Film Flush Mounted Probe

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□ HOW DOES A HOT WIRE SENSOR WORK

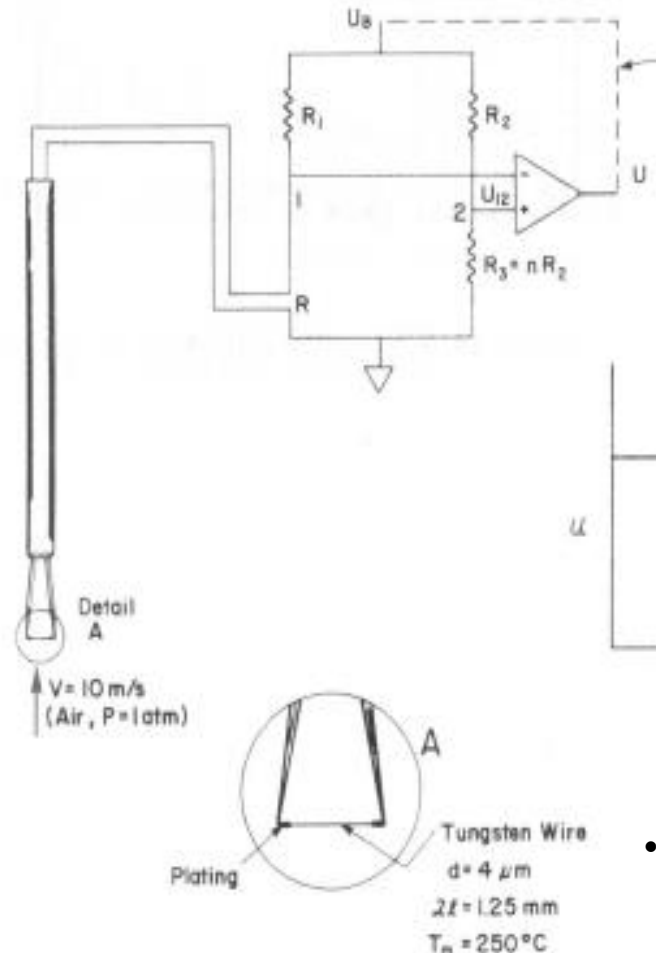
The electric current (i) flowing through the wire generates heat ($i^2 R_w$)

Flow Field
 V



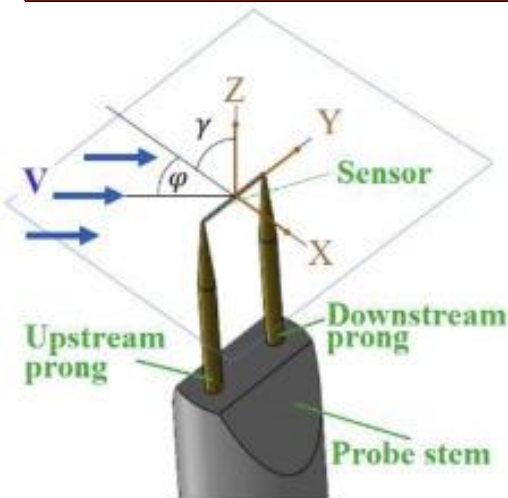
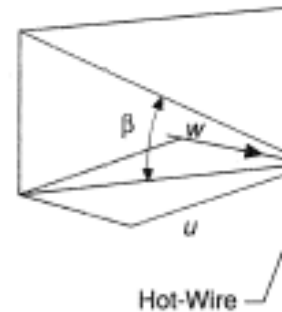
In equilibrium, this must be balanced by heat lost (primarily convective) to the surroundings.

Electric current, i ,
through wire



• Price: ~\$2750

❑ HOW DOES A HOT WIRE SENSOR WORK



Basic principle:

Heat transfer

Resistive heating:

$$q_{el} = \frac{E^2}{R_w} = I^2 R_w$$

E : voltage

I : current

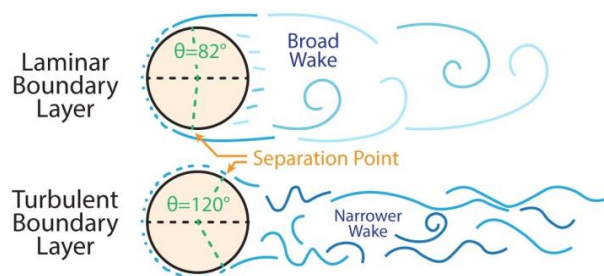
Heat loss to the environment through:

Radiation (often negligible)

$$q_s = f(T_w^4 - T_a^4)$$

a – ambient; w – wire

CONVECTIVE HEAT TRANSFER: CYLINDER



Conduction through prongs:

$$q_H = f(T_w, I_w, k_w, T_{prongs})$$

If $l \gg d \rightarrow$ negligible ($l/d > 200$)

Convection:

$$q_K = h A_w (T_w - T_a)$$

Nusselt number: $Nu = hd / k = f(Re, Pr, M, Gr, \text{direction})$

Reynolds number: $Re = \rho U d / \mu$

□ HOW DOES A HOT WIRE SENSOR WORK

- **Heat transfer characteristics:**

- **Convection** (nature convection, forced convection or mixed convection depending on Richardson numbers)
- **Conduction** to the supporting prong
- **Radiation:** <0.1%, is negligible.

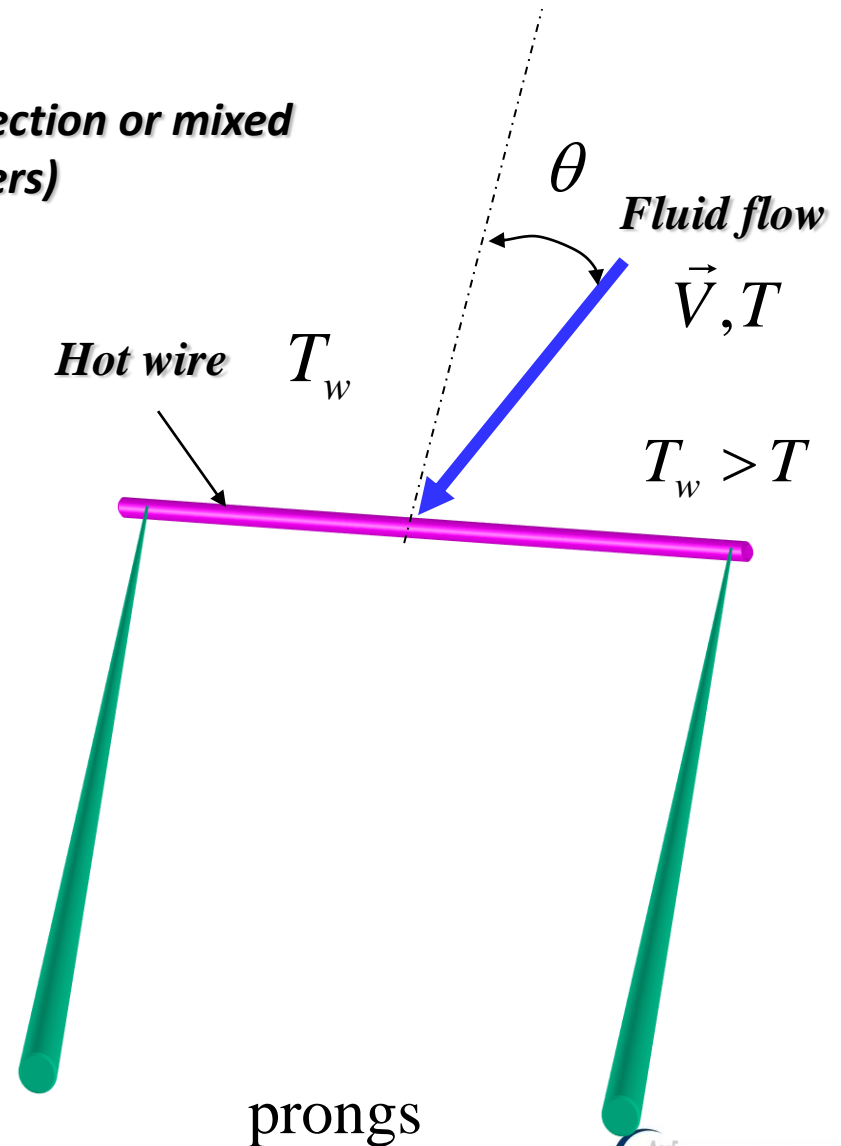
$$Nu = \frac{\dot{q}}{\pi d k (T_w - T)}$$
$$= Nu(Re, Pr, Gr, M, Kn, a_T, l/d, \theta)$$

$$Re = \frac{\rho U d}{\mu}; \quad Pr = \frac{\nu}{\gamma}$$

$$Gr = \frac{g \alpha (T_w - T) d^3}{\nu^2}; \quad M = \frac{V}{c}$$

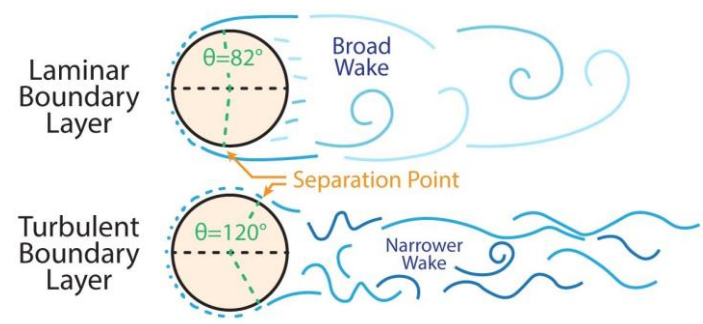
$$Kn = \frac{\lambda}{d} = \sqrt{\frac{1}{2} \pi c_p / c_v} \frac{M}{Re}$$

$$a_T = \frac{T_w - T}{T}$$



How a Hot Wire Sensor Works

CONVECTIVE HEAT TRANSFER: CYLINDER



• *Following King's Law (1915),*

$$Nu = (A + B Re^n) (1 + \frac{1}{2} a_T)^m$$

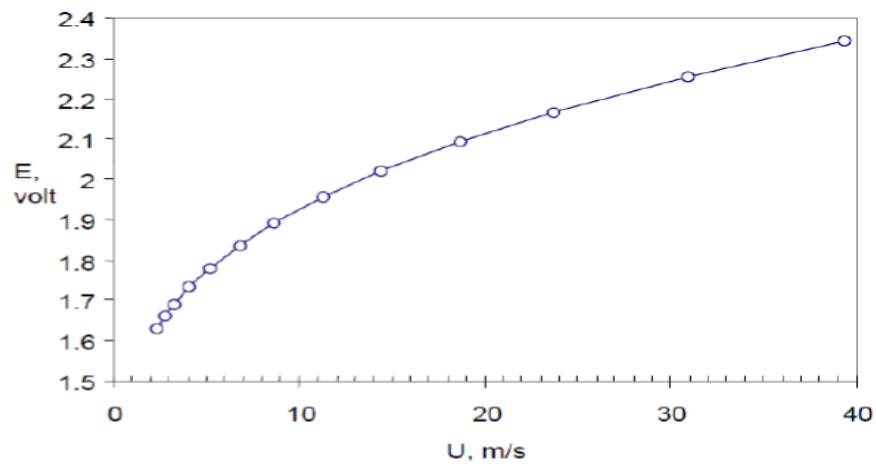
• *According to Collis and Williams (1959):*

$$Nu = (0.24 + 0.56 Re^{0.45}) (1 + \frac{1}{2} a_T)^{0.17}, \quad \text{for } 44 < Re < 140$$

$$Nu = 0.48 Re^{0.51} (1 + \frac{1}{2} a_T)^{0.17}, \quad \text{for } 0.02 < Re < 44$$

For a wire with constant temperature and a constant ambient temperature, one can develop a general relationship between voltage and velocity:

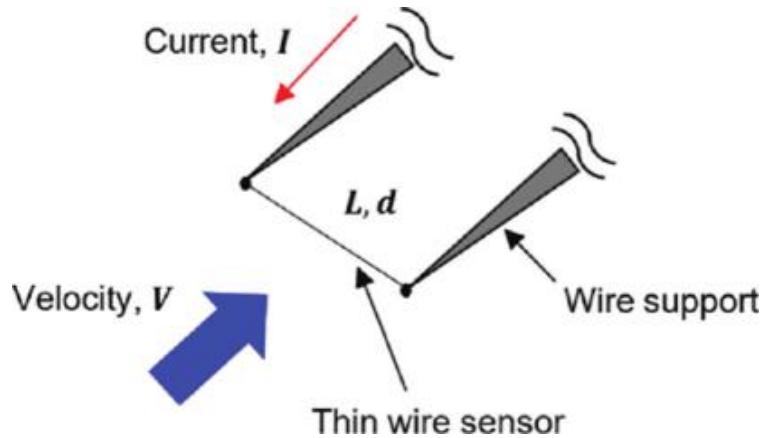
$$E^2 = A + BU^n \qquad \text{King's law}$$



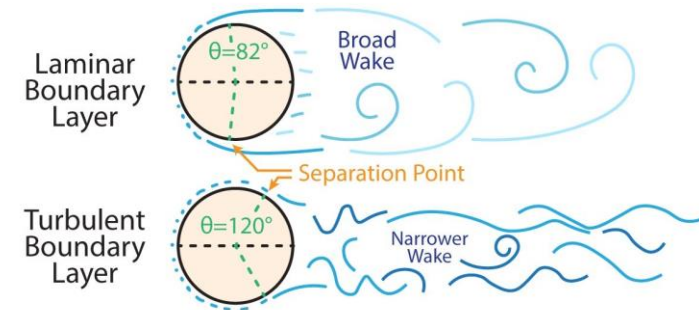
Coefficients are then obtained through calibration. Example of typical values:

	A	B	C	n	ε _U (%)
<i>E' = A + BUⁿ</i>					
<i>A, B, n</i> gleichzeitig gelöst	5,980	4,608	-	0,4137	0,11
schrittweise in <i>n</i>	6,018	4,587	-	0,4145	0,15
schrittweise in <i>A</i>	6,005	4,592	-	0,4143	0,15
<i>E' = A + BU^{0.5} + CU</i>	7,544	3,449	-0,005	0,5000	0,46

□ HOW A HOT WIRE SENSOR WORKS



CONVECTIVE HEAT TRANSFER: CYLINDER



- For a given sensor and fixed overheat ratio, The above equation can transfer as the relationship between the voltage output, E , of the hot-wire operation circuit and the flow velocity

$$\frac{E}{T_w - T} = A + BV^n$$

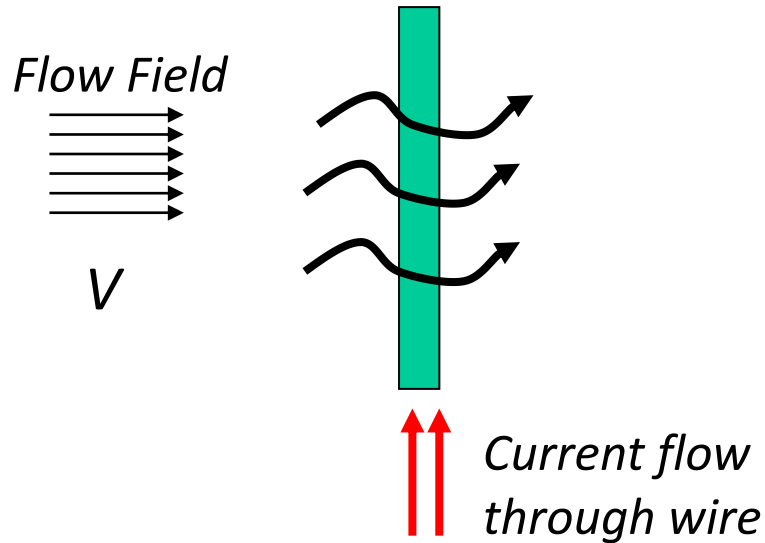
- Wire temperature cannot be measured directly, but can be estimated from its relationship to the wire resistance, R_w , directly measured by the operating bridge.
- For metallic wires:

$$R_w = R_r [1 + a_r (T_w - T)]$$

a_r : thermal resistivity coefficient

T_r : reference temepature

□ HOW A HOT WIRE SENSOR WORKS



- For a sensor placed in a unsteady flow, the unsteady energy equation will become:

$$mc \frac{dT_w}{dt} = i^2 R_w - \dot{q}(V, T_w)$$

m : the mass of the sensor

c : specifich heat of the sensor

\dot{q} : convectiveheat flux $\dot{q} = \dot{q}(V, T_w)$

The above equation has three unknowns: i , T_w (or R_w) and V

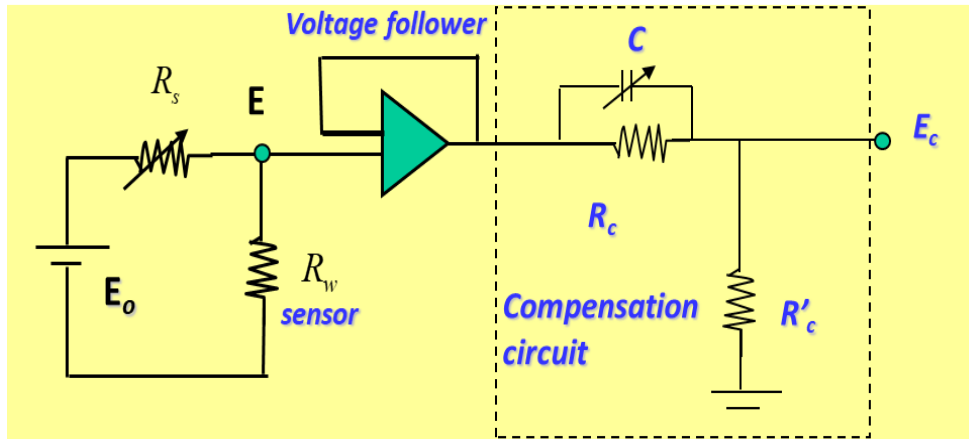
To render this equation solvable, one must keep with the electric current, i , or the sensor temperature (T_w) constant, which can be achieved with the use of suitable electric circuits.

The corresponding methods are known as:

(1). Constant Current Anemometry

(2). Constant Temperature Anemometry

❑ CONSTANT-CURRENT ANEMOMETRY (CCA)



$$mc \frac{dT_w}{dt} = i^2 R_w - \dot{q}(V, T_w) \quad \longrightarrow \quad \tau_w \frac{dT_w}{dt} + (T_w - T_{wop}) = K_T (V - V_{op})$$

τ_w : a time constant, which is proportional to the overheat ratio, and a static sensitivity, K_T

Since voltage, E , is proportional to, R_w , which, in turn, is linearly related to T_w , the linearized E-V relationship will be:

$$\tau_w \frac{dE}{dt} + (E - E_{op}) = K(V - V_{op})$$

τ_w : is usually $\sim 1\text{ms}$ for thin hot-wire and $\sim 10\text{ ms}$ for slim cylindrical hot-film.

- For flow with variable velocity or temperature, overheat ratio will vary as well.
- Flow low speed flow, it may result in “burnout”, for high-speed flow, sensitivity is low